# 行政院國家科學委員會專題研究計畫 成果報告

## 區間設限及左截資料下之自我一致與非參數最大概似估計 值 研究成果報告(精簡版)



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#### 中 華 民 國 101 年 09 月 03 日

- 中 文 摘 要 : 區間設限意指存活時間 T 僅知落於某區間[L,R]。某些情形 下,資料收集亦發生左截,即左截及區間設限資料。本研究 依據積分方程式,我們將提出 T 的存活函數之自我一致估計 值(SCE),並證明非參數最大概似估計值(NPMLE)滿足自我一 致積分方程式。經由模擬我們比較 SCE 和 NPMLE 之表現。我 們亦檢討 SCE 之一致性。
- 中文關鍵詞: 左截,區間設限,自我一致性

英 文 摘 要 :

英文關鍵詞:

### 行政院國家科學委員會補助專題研究計畫 5 成果報告 **□**期中進度報告

#### 區間設限及左截資料下之自我一致與非參數最大概似估計值

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中 華 民 國 101 年 07 月 29 日

#### Self-Consistent and Nonparametric Maximum Likelihood Estimators with Interval-Censored and Left-Truncated Data

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#### Abstract

Interval censoring refers to a situation in which,  $T_i^*$ , the time to occurrence of an event of interest is only known to lie in an interval  $[L_i^*, R_i^*]$ . In some cases, the variable  $T_i^*$  also suffers left-truncation. Based on an integral equation, we propose a self-consistent estimator (SCE) of survival function of  $T_i^*$ . It is shown that the nonparametric maximum likelihood estimator (NPMLE) is a solution of the integral equation. A simulation study is conducted to compare the performance between the SCE and NPMLE. We also discuss the consistency of the SCE.

Key Words: left truncation; interval censoring; self-consistent.

#### 1. Introduction

Left truncated and interval-censored data often arise in epidemiology and individual follow-up studies and possibly in other fields. Their importance stems from the common use of prevalent cohort study designs to estimate survival from onset of a specified disease. Consider the following example.

#### Example: AIDS Cohort Studies

In AIDS cohort studies, we are interested in the incubation time of the disease. An individual is selected only when he (or she) is HIV-positive and yet none have developed AIDS. Hence, earlier onset of AIDS would then be a truncating force for the variable of interest. Suppose that for each individual i the infection time (denoted by  $T_{si}$ ) can be quite accurately determined (e.g. due to blood transfusion). The recruitment starts at  $\tau_0$  and the follow-up is terminated at  $\tau_e$ . For each individual i, let  $T_i^*$  denote the time from  $T_{si}$  to development of AIDS. Let  $V_i^* = \tau_0 - T_{si}$  if  $T_{si} < \tau_0$  and  $V_i^* = 0$  if  $T_{si} \geq \tau_0$ . Hence,  $T_i^*$  is

observable only when  $T_i^* \geq V_i^*$ ). Let  $C_i^* = \tau_e - T_{si}$  denote the censoring times. Furthermore, there are many situations, in which the onset of AIDS is recorded only between an interval although the initiating events (HIV infection)  $T_{si}$  is recorded exactly. Hence, the variable of interest  $T_i^*$  can be recorded as an interval, say  $[L_i^*, R_i^*]$ . For example, under mixed case interval-censored model (Shick and Yu  $(2000)$ ), let K be a positive random integer, and for individual i let  $Y_i = \{Y_{i,k,j} : k = 1, 2, \ldots, j = 1, \ldots, k\}$  be an array of random variables such that  $Y_{i,k,1} < \cdots < Y_{i,k,k}$ . On the event  $K = k$ , let  $[L_i^*, R_i^*]$  denote the endpoints of that random interval among  $[-\infty, Y_{i,k,1}], [Y_{i,k,1}, Y_{i,k,2}], \ldots, [Y_{k,k}, \infty]$  which contains  $T_i^*$ . When  $T_i^*$ is right censoring, we have  $[L_i^*, R_i^*] = [Y_{k,k}, \infty) = [C_i^*, \infty]$ . Hence, one observes nothing if  $T_i^* \langle V_i^*, \text{ and observes } ([L_i^*, R_i^*], V_i^*) \text{ if } T_i^* \geq V_i^*.$  We assume that  $(K, Y_i, V_i^*)$  and  $T_i^*$  are independent and  $V_i^*$  is dependent of  $(L_i^*, R_i^*)$  with  $P(V_i^* \leq L_i^* | T_i^* \geq V_i^*) = 1$ . Let  $F(t)$  denote the distribution function of  $T_i^*$ , and  $G(x)$  and  $Q(x)$  denote the distribution function of  $V_i^*$ and  $C_i^*$ , respectively. For any distribution function W denote the left and right endpoints of its support by  $a_W = inf\{t : W(t) > 0\}$  and  $b_W = inf\{t : W(t) = 1\}$ , respectively. Throughout this article, for identifiability of  $T_i^*$ , we assume that  $T_i^*$ ,  $L_i^*$ ,  $R_i^*$  and  $V_i^*$  are all continuous, and

$$
a_G \le a_F \quad \text{and} \quad b_G \le b_F \le b_Q. \tag{1.1}
$$

Furthermore, we assume that  $P(L_i^* < R_i^*) = 1$  and given  $R_i^* < \infty$ ,  $(L_i^*, R_i^*)$  has a joint density  $b(l, r)$ , satisfying  $b(l, r) > 0$  if  $0 < F(l) < F(r) < 1$ .

Let  $(L_1, R_1, V_1), \ldots, (L_n, R_n, V_n)$  denote the left-truncated and interval-censored data. Note that  $[L_i, R_i] \subset [V_i, \infty]$ , i.e.  $V_i \leq L_i$ . The nonparametric maximum likelihood estimator (NPMLE) of  $F$  can be obtained by using EM algorithm of Turnbull (1976). When there is no truncation, the asymptotic properties of the NPMLE have been derived for intervalcensored data. Groeneboom and Wellner (1992) proposed an iterative convex minorant algorithm to calculate the NPMLE and proved the uniform consistency of the NPMLE when F is continuous and the joint distribution function of  $(L_i^*, R_i^*)$  is absolutely continuous. If  $(L_i^*, R_i^*)$  is continuous, the NPMLE converges slower than  $\sqrt{n}$  to a non-Gaussian limiting distribution (see Groeneboom and Wellner (1992), Shick and Yu (2000), van der Vaart and Wellner (2000), Song (2004)). Although asymptotic properties of the NPMLE have been derived for the interval-censored data without truncation, much less is known about the large sample properties of the NPMLE if both interval censoring and truncation are present. Pan and Chappell (1999) showed that the NPMLE is inconsistent when data is subject to case 1 interval censoring and left truncation. Under the assumption of monotonic hazard function, Pan et al. (1998) showed the consistency of the NPMLE when data is subject to left truncation and interval censoring.

In Section 2, based on an integral equation, we propose a self-consistent estimator (SCE) of survival function of  $T_i^*$ . We show that the NPMLE is a solution of the proposed integral equation. We discuss the consistency of the SCE. In Section 3, a simulation study is conducted to compare the performance between the SCE and NPMLE.

#### 2. The Nonparametric Estimators

#### 2.1 The NPMLE

In this section, we briefly review the NPMLE of  $S_F(t) = P(T_i^* > t)$  using EM algorithm of Turnbull (1976). Notice that due to sampling scheme described in Section 1, we have  $P([L_i, R_i] \subset [V_i, \infty)) = 1$ . Without loss of generality, suppose the observed data are ordered according to  $L_i$  such that  $L_1 < L_2 < \cdots < L_n$ . Following Turnbull (1976), Frydman (1994) and Alioum and Commenges (1996), we consider nonparametric estimation of F using the  $n$ independent pairs  $\{A_1, B_1\}, \ldots, \{A_n, B_n\}$ , where  $A_i = [L_i, R_i]$  and  $B_i = [V_i, \infty)$ . Assuming that the inspection process which gives rise to  $A_i$  is independent of  $T_i$ , we consider the following conditional likelihood:

$$
L_c(S_F) = \prod_{i=1}^n \frac{P_{S_F}(A_i)}{P_{S_F}(B_i)},
$$
\n(2.1)

where  $P<sub>S</sub>(R)$  denotes the probability that is assigned to the interval by  $S<sub>F</sub>$ . We define an NPMLE as  $\hat{S}_M = \text{argmax}_{S \in \mathcal{S}} \{L_c(S)\}\$ , where S denotes the class of survival functions such that  $P_S(\bigcup_{i=1}^n B_i) = 1$  and  $L_c(S)$  is defined, i.e.  $P_S(B_i) > 0$  for all  $i = 1, ..., n$ . Using the approach of Hudgens (2005), we define  $\mathcal{K} = \{K_1, K_2, \ldots, K_{2n}\}\,$ , where  $K_1 = A_i$  for  $i = 1, \ldots, n$ , and  $K_i = (-\infty, V_i)$  for  $i = n + 1, \ldots, 2n$ . An intersection graph for K is constructed as follows. For each element of  $K$ , we define a corresponding vertex. Let i be the label of the vertex corresponding to  $K_i$ . Denote the set of vertex by  $S_v$ . Two vertices in  $S_v$  are considered connected by an edge if and only if the two corresponding regions in K intersect. A clique is defined as a subset M of  $S_v$  such that every member of M is connected by an edge to every other member of  $M$ . A maximal clique has the additional property that it is not a proper subset of any other clique. Let  $\mathcal{M} = \{M_1, \ldots, M_J\}$  be the subset of maximal cliques of  $S_v$  that contain at least one vertex corresponding to a censoring interval, i.e. for each  $M_j \in \mathcal{M}$ , there is some  $i \in \{1, \ldots, n\}$  such that  $i \in M_j$ . Let

 $\mathcal{H} = \{H_1, \ldots, H_J\}$  be the corresponding set of real representations of elements of M where  $H_j = \bigcap_{i \in M_j} K_i$  for  $j = 1, ..., J$ . By Lemma 1 of Hudgens (2005), any distribution function which increases outside  $\cup_{j=1}^{J} H_j$  cannot be an NPMLE. By Lemma 2 of Hudgens (2005), for fixed value of  $P_F(H_j)$ , the likelihood is independent of the values of F within the region  $H_j$ . These lemmas allow us to consider maximizing a simpler likelihood than equation (2.1). For each  $H_j \in \mathcal{H}$ , let  $s_j = P_F(H_j)$  and let **s** be an m-dimension column vector with elements  $s_j$ . We shall assume throughout that  $H_1, \ldots, H_J$  are ordered such that  $H_j = [q_j, p_j]$  is to the left of  $H_{j+1} = [q_{j+1}, p_{j+1}]$  for  $j = 1, ..., J-1$ , i.e.  $[q_1, p_1]$ ,  $[q_2, p_2]$ , ...,  $[q_j, p_j]$ , where  $q_1 \leq p_1 < q_2 \leq p_2 < \cdots < q_J \leq p_J$ . It follows that from lemmas 1 and 2 of Hudgens (2005)

$$
L_c(\mathbf{s}) = \prod_{i=1}^n \frac{\sum_{j=1}^J \alpha_{ij} s_j}{\sum_{j=1}^J \beta_{ij} s_j},
$$
\n(2.2)

where  $\alpha_{ij} = I[H_j \subset A_i], \beta_{ij} = I[H_j \subset B_i]$  and  $I[\cdot]$  is the usual indicator function. The resulting reduced likelihood (2.2) is exactly as described in section 2 of Alioum and Commenges (1996). The goal is to maximize likelihood (2.2) subject to the constraints

that maximizing likelihood (2.1) is equivalent to maximizing

$$
\sum_{j=1}^{J} s_j = 1,\tag{2.3}
$$

$$
s_j \ge 0 \ (j = 1, ..., J), \tag{2.4}
$$

and

$$
\sum_{j=1}^{J} \alpha_{ij} s_j > 0, \ (i = 1, \dots, n). \tag{2.5}
$$

We shall use  $\Omega$  to denote the parameter space that is given by constraints  $(2.3)-(2.5)$ , i.e.

$$
\Omega = \{ \mathbf{s} \in R^J : \sum_{j=1}^J s_j = 1; s_j \ge 0 \text{ for } j = 1, \dots, J; \sum_{j=1}^J \alpha_{ij} s_j > 0 \text{ for } i = 1, \dots n \}.
$$

To find the maximum likelihood estimate of the vector s, we can use an EM algorithm and the resulting self-consistent estimate of s is exactly the Turnbull's (1976) self-consistency algorithm as follows:

$$
s_j^{(b)} = \left\{ 1 + \frac{d_j(s^{(b-1)})}{M(s^{(b-1)})} \right\} s_j^{(b-1)} \ (1 \le j \le J), \tag{2.6}
$$

where

$$
d_j(s^{(b-1)}) = \sum_{i=1}^n \left\{ \left( \alpha_{ij} / \sum_{k=1}^J \alpha_{ik} s_k^{(b-1)} \right) - \left( \beta_{ij} / \sum_{k=1}^J \beta_{ik} s_k^{(b-1)} \right) \right\},
$$

and

$$
M(s^{(b-1)}) = \sum_{i=1}^{n} \frac{1}{\sum_{j=1}^{J} \beta_{ij} s_j^{(b-1)}}.
$$

Let  $\hat{s}_j$   $(j = 1, \ldots, J)$  denote the estimators obtained from (2.6). As pointed out by Hudgens (2005), in general, a maximizer of  $L_c(s)$  subject to  $s \in \Omega$  need not exist since  $\Omega$  is not closed. For left-truncated and interval-censored data, Hudgens (2005) (see Theorem 1, page 578) proposed a sufficient and necessary condition for the existence of the NPMLE as follows:

" There is a maximizer of  $L_c(s)$  subject to  $s \in \Omega$  if and only if for each non-empty proper subset S of  $\{1,\ldots,n\}$  there is an  $i \notin S$  such that  $\mathcal{A}_i \subset \mathcal{D}_S$ ,  $\mathcal{A}_i = \cup_{j \in A_i^*} H_j$ ,  $\mathcal{D}_S = \cup_{k \in S} \mathcal{B}_k$ ,  $\mathcal{B}_k = \bigcup_{j \in B_k^*} H_j$ , where  $A_i^* = \{j : \alpha_{ij} = 1\}$  and  $B_k^* = \{j : \beta_{kj} = 1\}$ ". Based on the the estimators  $\hat{s}_j$ 's, an estimator  $\hat{S}_M(t)$  of  $S_F(t)$  can be uniquely defined for  $t \in [p_j, q_{j+1})$ by  $\hat{S}_M(p_j) = \hat{S}_M(q_{j+1}-) = 1 - (\hat{s}_1 + \cdots + \hat{s}_j)$ , but is not uniquely defined for t being in an open innermost interval  $(q_j, p_j)$  with  $q_j < p_j$ . To avoid ambiguity we define  $\hat{S}_M(t)$  $1 - [\hat{s}_1 + \cdots + \hat{s}_{j-1} + s_j(t - q_j)/(p_j - q_j)]$  if  $t \in (q_j, p_j]$  and  $0 < q_j < p_j < \infty$ .

#### 2.2 The SCE

Let  $S_F(t) = 1 - F(t)$  denote the survival function of T and  $p = P(V_i^* \leq T_i^*)$  denote the proportion of un-truncation. We have the following equation:

$$
S_F(t) = P(T_i^* > t, V_i^* \le t) + P(T_i^* > t, V_i^* > t)
$$
  
=  $pP(V_i^* \le t < L_i^* | T_i^* \ge V_i^*) + pP(T_i^* > t, L_i^* < t \le R_i^* | T_i^* \ge V_i^*) + P(T_i^* > t, V_i^* > t).$  (2.7)

Motivated by  $(2.7)$ , given p, we consider the following self-consistent estimator:

$$
\hat{S}(t) = \frac{1}{np^{-1}} \left\{ \sum_{i=1}^{n} I_{[V_i \le t < L_i]} + \sum_{i=1}^{n} I_{[L_i \le t < R_i]} \frac{\hat{S}(t) - \hat{S}(R_i)}{\hat{S}(L_i) - \hat{S}(R_i)} + \sum_{i=1}^{n} I_{[V_i > t]} \frac{\hat{S}(t)}{\hat{S}(V_i)} \right\}.
$$
\n(2.8)

Notice that the last term of the equation (2.8) is to recover the missing information due to left-truncation. Given the observation  $V_i > t$ , a pseudo observation is recovered by adding the weight  $\hat{S}(t)/\hat{S}(V_i)$ . Let  $\tilde{G}(t) = P(V_i \leq t)$  denote the sub-distribution function of  $V_i$ . Since  $\tilde{G}(t) = p^{-1} \int_0^t 1/S_F(V_i) dG(t)$ . It follows that  $np^{-1}$  can be estimated by  $\sum_{i=1}^n 1/S_F(V_i)$ (see Shen (2005)). Hence, a self-consistent estimator  $\hat{S}_n$  is given by solving the following equation:

$$
\hat{S}_n(t) = \left[\sum_{i=1}^n \frac{1}{\hat{S}_n(V_i)}\right]^{-1} \left\{\sum_{i=1}^n I_{[V_i \le t < L_i]} + \sum_{i=1}^n I_{[L_i \le t < R_i]} \frac{\hat{S}_n(t) - \hat{S}_n(R_i)}{\hat{S}_n(L_i) - \hat{S}_n(R_i)} + \sum_{i=1}^n I_{[V_i > t]} \frac{\hat{S}_n(t)}{\hat{S}_n(V_i)}\right\}.
$$
\n(2.9)

Let  $\tilde{G}_n(v)$  denote the empirical version of  $\tilde{G}(v)$ . Similarly, Let  $\tilde{H}_n(v, l)$  and  $\tilde{Q}_n(l, r)$  denote the empirical versions of the joint sub-distributions of  $\tilde{H}(v, l) = P(V_i \le v, L_i \le l)$  and  $Q(l, r) = P(L_i \leq l, R_i \leq r)$ , respectively. It follows that (2.9) can be written as

$$
\hat{S}_n(t) =
$$

$$
\bigg[\int \frac{1}{\hat{S}_n(v)} \tilde{G}_n(dv)\bigg]^{-1} \bigg\{\int_{v \le t < l} \tilde{H}_n(dv, dl) + \int_{l \le t < r} \frac{\hat{S}_n(t) - \hat{S}_n(r)}{\hat{S}_n(l-) - \hat{S}_n(r)} \tilde{Q}_n(dt, dr) + \int_{v > t} \frac{\hat{S}_n(t)}{\hat{S}_n(v)} \tilde{G}_n(dv)\bigg\}.
$$

The following theorem shows that  $\hat{S}_M$  satisfies the equation (2.9).

#### Theorem 1.

The NPMLE  $\hat{S}_M$  satisfies equation (2.9).

#### Proof:

First, consider an initial estimator  $\hat{S}_n^{(0)}$ , which puts mass only on  $[q_j, p_j]$   $(j = 1, \ldots, J)$ . Let  $\hat{S}_n^{(1)}$  denote the first step estimator. Without changing the innermost intervals and likelihood function, we can transform data by moving all right censored and left truncated points between  $p_{j-1}$  and  $q_j$  to  $p_{j-1}$ . Similarly, move all left censored points between  $p_{j-1}$ and  $q_j$  to  $q_j$ . (see Li et al. (1997)). Based on the transform data, for all i, j, we have  $I_{[p_{j-1} < V_i \leq q_j]} = 0, I_{[V_i \leq p_{j-1} \leq L_i]} I_{[q_j > L_i]} = 0, I_{[V_i \leq p_{j-1} \leq L_i]} I_{[q_j > L_i]} = 0, I_{[V_i > p_{j-1}]} I_{[V_i \leq q_j - \leq L_i]} = 0,$  $I_{[L_i \leq p_{j-1} < R_i]} = 0$  and  $I_{[L_i \leq q_j - \leq R_i]} = 0$ . It follows that  $\hat{S}_n^{(1)}(p_{j-1}) - \hat{S}_n^{(1)}(q_j-) = 0$ . Hence,  $\hat{S}_n^{(1)}$  also puts mass only on  $[q_j, p_j]$   $(j = 1, \ldots, J)$ . Next, since there is no left censoring observations in  $(q_j, p_j]$  and there is no left truncation observations in  $(q_j, p_j)$ , we have for all  $i, j, I_{[V_i \le q_j < L_i]} I_{[p_j \ge L_i]} = 0$  and  $I_{[V_i > q_j]} I_{[V_i \le p_j < L_i]} = 0$ . Furthermore, given an interval  $[L_i, R_i]$ , we either have  $[q_j, p_j] \subseteq [L_i, R_i]$  or  $[q_j, p_j] \cap [L_i, R_i] = \emptyset$ . Thus, we have

$$
\hat{S}_{n}^{(1)}(q_{j}) - \hat{S}_{n}^{(1)}(p_{j}) = \left[\sum_{i=1}^{n} \frac{1}{\hat{S}_{n}^{(0)}(V_{i})}\right]^{-1} \left\{\sum_{i=1}^{n} I_{[[q_{j},p_{j}] \in ([L_{i},R_{i}]]} \frac{\hat{S}_{n}^{(0)}(q_{j}) - \hat{S}_{n}^{(0)}(p_{j})}{\hat{S}_{n}^{(0)}(L_{i}) - \hat{S}_{n}^{(0)}(R_{i})} + \sum_{i=1}^{n} \frac{\hat{S}_{n}(q_{j}) - \hat{S}_{n}(p_{j})}{\hat{S}_{n}(V_{i})} - \sum_{i=1}^{n} I_{[V_{i} \leq q_{j}]} \frac{\hat{S}_{n}(q_{j})}{\hat{S}_{n}(V_{i})} + \sum_{i=1}^{n} I_{[V_{i} \leq p_{j}]} \frac{\hat{S}_{n}(p_{j})}{\hat{S}_{n}(V_{i})}\right\}.
$$
\n(2.10)

Since there is no left truncation observations in  $[q_j, p_j]$ , (2.10) can be written as

$$
\hat{S}_{n}^{(1)}(q_{j}) - \hat{S}_{n}^{(1)}(p_{j}) = \left[\sum_{i=1}^{n} \frac{1}{\hat{S}_{n}^{(0)}(V_{i})}\right]^{-1} \left\{\sum_{i=1}^{n} I_{[[q_{j},p_{j}] \in ([L_{i},R_{i}]]} \frac{\hat{S}_{n}^{(0)}(q_{j}) - \hat{S}_{n}^{(0)}(p_{j})}{\hat{S}_{n}^{(0)}(L_{i}) - \hat{S}_{n}^{(0)}(R_{i})} + \sum_{i=1}^{n} \frac{\hat{S}_{n}(q_{j}) - \hat{S}_{n}(p_{j})}{\hat{S}_{n}(V_{i})} - \sum_{i=1}^{n} I_{[q_{j} \ge V_{i}]} \frac{\hat{S}_{n}(q_{j}) - \hat{S}_{n}(p_{j})}{\hat{S}_{n}(V_{i})}\right\}.
$$
\n(2.11)

Next,

$$
\hat{S}_M(q_j-) - \hat{S}_M(p_j) = \left[\sum_{i=1}^n \frac{1}{\sum_{j=1}^J \beta_{ij} s_j}\right]^{-1} \left\{\sum_{i=1}^n \frac{\alpha_{ij}}{\sum_{k=1}^J \alpha_{ik} \hat{s}_k} + \sum_{i=1}^n \frac{1-\beta_{ij}}{\sum_{k=1}^J \beta_{ik} \hat{s}_k}\right\} \hat{s}_j. (2.12)
$$

By definitions of  $A_i$ ,  $B_i$ ,  $\alpha_{ij}$  and  $\beta_{ij}$ , it follows that equation (2.11) is equivalent to equation (2.12). The proof is completed.

Although the NPMLE  $\hat{S}_M$  satisfies equation (2.9), it is not clear whether the SCE is consistent or not. We discuss the consistency of the SCE as follows.

Let  $\Omega$  be the event  $\{\lim \tilde{H}_n(v,l) = \tilde{H}(v,l), \lim \tilde{Q}_n(l,r) = \tilde{Q}(l,r) \text{ uniformly for all } v < l <$ r}. For each  $\omega \in \Omega$ , let  $\hat{S}_n$  be the solution of (2.9). Since  $\{\hat{S}_n\}_{n\geq 1}$  is bounded and monotone, for each subsequence of natural numbers, by Helly's selection theorem, there exists a further subsequence, say  $\{n_k\}$ , such that  $\lim_{n_k\to\infty} \hat{S}_{n_k}(t) = S_0(t)$  pointwisely for some  $S_0 \in \Theta$ . Thus, it suffices to show that  $S_0(t) = S_F(t)$  for all  $t \in [a_F, b_F]$ .

Since  $\tilde{H}_n$  and  $\tilde{Q}_n$  converge uniformly to  $\tilde{H}$  and  $\tilde{Q}$ , respectively and  $\hat{S}_n$  satisfies (2.9), by the bounded convergence theorem  $S_0$  satisfies the following equation:  $S_0(t)$  =

$$
\bigg[\int \frac{1}{S_0(v)} \tilde{G}(dv)\bigg]^{-1} \bigg\{ \int_{v \le t < l} d\tilde{H}(v, l) + \int_{l \le t < r} \frac{S_0(t) - S_0(r)}{S_0(l) - S_0(r)} \tilde{Q}(dl, dr) + \int_{v > t} \frac{S_0(t)}{S_0(v)} \tilde{G}(dv) \bigg\}.\tag{2.13}
$$

Equation (2.13) can be written as

$$
S_0(t) \int_{v \le t} \frac{1}{S_0(v)} \tilde{G}(dv) = \int_{v \le t < l} \tilde{H}(dv, dl) + \int_{l \le t < r} \frac{S_0(t) - S_0(r)}{S_0(l) - S_0(r)} \tilde{Q}(dl, dr). \tag{2.14}
$$

Let  $H(v, l) = P(V_i^* \le u, L_i^* \le l)$  and  $Q(l, r) = P(L_i^* \le r, R_i^* \le r)$ . Since  $\tilde{G}(dv)$  =  $p^{-1}S_F(v)G(dv)$ ,  $\tilde{H}(dv, dl) = p^{-1}S_F(l)H(dv, dl)$ , and  $\tilde{Q}(dl, dr) = p^{-1}[S_F(l) - S_F(r)]Q(dl, dr)$ , (2.14) can be written as

$$
p^{-1}S_0(t)\int_{v\leq t}\frac{S_F(v)}{S_0(v)}G(dv) = p^{-1}\int_{v\leq t
$$

$$
+p^{-1} \int_{l \le t < r} \frac{S_0(t) - S_0(r)}{S_0(l) - S_0(r)} [S_F(l) - S_F(r)] Q(dv, dl, dr). \tag{2.15}
$$

Replacing  $S_0(\cdot)$  of (2.15) by  $S_F(\cdot)$ , we obtain

$$
p^{-1}S_F(t)G(t) = p^{-1} \int_{v \le t < l} S_F(l)H(dv, dl) + p^{-1} \int_{l \le t < r} [S_F(t) - S_F(r)]Q(dl, dr). \tag{2.16}
$$

Note that (2.16) is equivalent to

$$
P(T_i^* > t, V_i^* \le t | T_i^* \ge V_i^*) = P(V_i^* \le t < L_i^* | T_i^* \ge V_i^*) + P(T_i^* > t, L_i^* < t < R_i^* | T_i^* \ge V_i^*).
$$

Subtracting  $(2.16)$  from  $(2.15)$ , we obtain

$$
h(t)K(t) =
$$
  
\n
$$
S_0(t)\int_{v\leq t} \frac{h(v)}{S_0(v)}G(dv) - \int_{l\leq t\n(2.17)
$$

where  $K(t) = G(t) - P(L_i^* \leq t < R_i^*)$  and  $h(t) = S_0(t) - S_F(t)$ . Hence, to obtain the consistency of the SCE, one need the following condition:

If (2.17) holds on 
$$
t \in (a_F, b_F)
$$
 then  $h(t) = 0$  for  $t \in (a_F, b_F)$   $(2.18)$ .

Hence, if (2.18) holds, we have  $S_0(t) = S_F(t)$ . Since all limit points of  $\hat{S}_n$  must satisfy (2.15), by Helly-Bray selection theorem we have  $\hat{S}_n(t) \to S_F(t)$  a.s. for  $t \in (a_F, b_F)$  and  $\sup_{t\in(a_F,b_F)}|\hat{S}_n(t)-S_F(t)|\to 0$  a.s if  $\hat{S}_n$  is a sequence of monotone, right continuous and bounded functions on  $(a_F, b_F)$ .

Similar to doubly censored data (see Gu and Zhang (1993)) condition (2.18) may hold if one can show that suppose  $K(t) > 0$  holds on  $\{t : 0 < S(t) < 1\}$  then  $h(t) = 0$  for all t provided that  $h(t+) \neq h(t) \Rightarrow S(t+) < S(t)$  on  $\{t : 0 < S(t) < 1\}$ ,  $h(t) = 0$  on  ${t : S(t) = 0 \text{ or } S(t) = 1}.$  Although we are not able to establish the consistency of the SCE, the simulation study in Section 3 indicate that the SCE performs adequately.

#### 3. Simulation Results

A simulation study is conducted to investigate the performance of the proposed estimator  $\hat{F}(t)$ . The  $T_i^*$ 's are i.i.d. exponential distributed with mean equal to 1. The  $V_i^*$ 's are i.i.d. exponential distributed with scale parameters  $\theta = 1, 2$  and 4, i.e.  $G(x; \theta) = 1 - \exp(-x\theta)$ 

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for  $x > 0$ . The  $T_i^*$  and  $V_i^*$  are independent to each other. To make the truncated sample interval-censored, we first generate a random variable  $X_i = 2 + B(n_c, 0.5)$ , where  $B(n_c, 0.5)$ is a binomial random variable with  $n_c = 5, 8$ . Given  $X_i = k$ , we then generate k i.i.d uniform random variables  $U_{ji} \sim U(0,1)$   $(j = 1, ..., k)$ . Define  $Z_{1i} = V_i^* + U_{1i}$ ,  $Z_{2i} = U_{2i} + Z_{1i}$ ,  $Z_{3i} = U_{3i} + Z_{2i}, \dots, Z_{ki} = Z_{k-1,i} + U_{ki}$ . We keep the sample if  $T_i^* \geq V_i^*$  and regenerate a sample if  $T_i^* < V_i^*$ . If  $T_i^*$  falls in the interval  $[Z_{ji}, Z_{j+1,i}]$   $(j = 1, \ldots, k-1)$ , then let  $L_i^* = Z_{ji}$ and  $R_i^* = Z_{j+1,i}$ . If  $T_i^* > Z_{k,i}^*$  then let  $L_i^* = Z_{k,i}$  and  $R_i^* = 10000$ . The goal is to estimate  $S(t_p) = p$ , with  $p = 0.8, 0.5$  and 0.2. Based on left-truncated and interval-censored data  $(V_i, L_i, R_i)$   $(i = 1, ..., n)$ , we obtain the proposed estimator  $\hat{S}_n(t_p)$  and the NPMLE  $\hat{S}_M(t_p)$ . For both estimators, the initial estimator is the product-limit estimator for left-truncated and right-censored data (see Wang (1987)) based on midpoint imputation. The convergence criterion was set  $|\hat{S}_{M}^{(r+1)}(t_p) - \hat{S}_{n}^{(r)}(t_p)| < 0.001$  or  $|\hat{S}_{n}^{(r+1)}(t_p) - \hat{S}_{n}^{(r)}(t_p)| < 0.001$ . The sample sizes are chosen as 200 and 400. The replication is 1000 times. Tables 1 through 3 show the empirical biases, standard deviations (std.) and root mean squared errors (rmse) of  $\hat{S}_n$  and  $\hat{S}_M$ . Tables 1 through 3 also list the proportion of truncation  $P(T_i^* \lt V_i^*)$  (denoted by  $q_T$ ). Based on the results of Tables 1 through 3, we conclude that:

(i) Given  $q_T$ , the rmse of the estimators  $\hat{S}_n$  and  $\hat{S}_M$  increase as  $n_c$  decreases, i.e. mean interval length increases.

(ii) The biases of the estimators  $\hat{S}_n$  are larger than that of  $\hat{S}_M$  for most of the cases considered. In terms of rmse, the NPMLE  $\hat{S}_M$  outperforms the SCE  $\hat{S}_n$ . When  $n = 400$ , the performance of the estimators  $\hat{S}_n$  and  $\hat{S}_M$  are close to each other for most of the cases considered.

Table 1. Simulation results for bias, standard deviation and

	root mean squared error for estimating $S(t_{0,2})$								
				$S_n(t_{0.2})$	$S_M(t_{0.2})$				
θ	$n_c$	$\, n$	$q_T$	bias std rmse	bias std rmse				
	5	200	0.50	$-0.016$ $0.029$ $0.033$	$-0.010$ $0.029$ $0.031$				
1	5	400	0.50	$-0.009$ $0.020$ $0.022$	$-0.008$ 0.019 0.021				
1	8	200	0.50	$-0.014$ $0.029$ $0.032$	$-0.012$ $0.028$ $0.030$				
	8	400	0.50	$-0.006$ $0.018$ $0.020$	$-0.008$ $0.017$ $0.019$				
$\overline{2}$	5	200	0.43	$-0.012$ 0.039 0.041	$-0.010$ $0.037$ $0.037$				
2	5	400	0.43	$-0.009$ $0.021$ $0.022$	$-0.006$ $0.020$ $0.022$				
$\mathcal{D}_{\mathcal{L}}$	8	200	0.43	-0.013 0.036 0.038	$-0.012\;0.036\;0.038$				
2	8	400	0.43	$-0.007$ $0.021$ $0.022$	$-0.008$ $0.020$ $0.021$				
4	5	200	0.31	$-0.011$ $0.037$ $0.039$	$-0.007$ $0.035$ $0.036$				
4	5	400	0.31	$-0.005$ $0.021$ $0.022$	$-0.006$ $0.020$ $0.021$				
$\overline{4}$	8	200	0.31	$-0.015$ 0.035 0.040	$-0.012$ 0.035 0.037				
4	8	400	0.31	$-0.007$ 0.019 0.020	$-0.009$ $0.018$ $0.020$				

Table 2. Simulation results for bias, standard deviation and

	Toot incall squared error for estimating $D(v_{0.5})$								
				$S_n(t_{0.5})$		$S_M(t_{0.5})$			
$\theta$	$n_c$	$\boldsymbol{n}$	$q_T$	bias	std	rmse	bias	std	rmse
	5	200	0.50			$-0.008$ $0.059$ $0.060$	$-0.006$ 0.057 0.057		
1	5	400	0.50			$-0.010$ $0.025$ $0.027$	$-0.007$ $0.025$ $0.026$		
	8	200	0.50			$-0.012$ 0.057 0.058	$-0.013$ 0.055 0.057		
1	8	400	0.50			$-0.008$ $0.022$ $0.023$	$-0.009$ $0.021$ $0.023$		
$\overline{2}$	5	200	0.43			$-0.023$ $0.055$ $0.060$	$-0.018$ 0.053 0.056		
$\overline{2}$	5	400	0.43	$-0.012$ 0.038 0.041			$-0.010$ $0.037$ $0.038$		
$\overline{2}$	8	200	0.43			$-0.026$ $0.053$ $0.059$	$-0.021$ $0.051$ $0.055$		
$\overline{2}$	8	400	0.43			$-0.014$ 0.036 0.038	$-0.011$ $0.036$ $0.038$		
$\overline{4}$	5	200	0.31			$-0.036$ $0.067$ $0.076$	$-0.031$ $0.064$ $0.072$		
4	5	400	0.31	$-0.016$ $0.040$ $0.041$			$-0.019$ $0.037$ $0.039$		
$\overline{4}$	8	200	0.31			$-0.031$ $0.064$ $0.071$	$-0.026$ 0.062 0.067		
4	8	400	0.31			$-0.013$ 0.037 0.039	$-0.012$ 0.036 0.038		

root mean squared error for estimating  $S(t_0, \cdot)$ 

	root mean squared error for estimating $S(t_{0.8})$								
				$S_n(t_{0.8})$		$\hat{S}_{M}(t_{0.8})$			
$\theta$	$n_c$	$\it n$	$q_T$	bias	std rmse	bias	std	rmse	
	5	200	0.50		$-0.012$ 0.048 0.049	$-0.009$ $0.046$ $0.047$			
1	5	400	0.50		$-0.008$ $0.027$ $0.028$	$-0.005$ 0.026 0.026			
	8	200	0.50		$-0.010$ $0.045$ $0.046$	$-0.007$ $0.045$ $0.046$			
1	8	400	0.50		$-0.009$ $0.026$ $0.027$	$-0.005$ 0.025 0.025			
$\mathcal{D}_{\mathcal{L}}$	5	<b>200</b>	0.43		$-0.032$ $0.069$ $0.076$	$-0.027$ 0.067 0.072			
2	5	400	0.43		$-0.017$ $0.041$ $0.044$	$-0.021$ $0.040$ $0.045$			
$\mathcal{D}_{\mathcal{L}}$	8	200	0.43		$-0.029$ 0.066 0.072	$-0.030$ $0.065$ $0.072$			
$\overline{2}$	8	400	0.43		$-0.016$ 0.039 0.042	$-0.020$ $0.038$ $0.043$			
4	5	200	0.31		$-0.041$ $0.073$ $0.083$	$-0.039$ $0.069$ $0.080$			
4	5	400	0.31		$-0.023$ 0.048 0.053	$-0.019$ 0.046 0.050			
$\overline{4}$	8	200	0.31		$-0.032$ 0.070 0.077	$-0.035$ 0.067 0.076			
4	8	400	0.31		$-0.021$ 0.046 0.051	$-0.020$ $0.045$ $0.049$			

Table 3. Simulation results for bias, standard deviation and

#### 4. Applications

For purpose of illustration, we apply both estimators to the CDC AIDS Blood Transfusion Data. The AIDS Blood Transfusion Data are collected by the Centers for Disease Control (CDC), which is from a registry data base, a common source of medical data (see Kalbfleish and Lawless (1989)). The data were retrospectively ascertained for all transfusion-associated AIDS cases in which the diagnosis of AIDS occurred prior to the end of of the study, which was June 30, 1991. The data consist of the time in month and only cases having either one transfusion or multiple transfusions in the same calendar month were used. Cases having the AIDS prior to July 1, 1982  $(\tau_0)$  were not included because this is when adults started being infected by the virus from a contaminated blood transfusion. Because HIV was unknown prior to 1982, and cases of transfusion-related AIDS before  $\tau_0$  would have been missed (i.e. left-truncated). Let  $T_{si}$  be the calendar time (in years) of the initiating events (HIV infection), and  $\tau_D$  be the calendar time (in years) at which AIDS is diagnosed. Let  $T_i^*$  =  $12(\tau_D - T_{si})$  (in month) be the incubation time from HIV infection to AIDS. Let  $V_i^* =$  $12(\tau_0 - T_{si})$  (in month) denote the left-truncated variable. Hence,  $T_i^*$  is observable only when  $T_i^* \geq V_i^*$ ). There were 295 truncated observations. To introduce interval censoring, similar to the setup in simulation study, we generate a random variable  $X = 2 + B(6, 0.8)$ . Given  $X_i = k$ , we then generate k i.i.d uniform random variables  $U_{ji} \sim U(0, 1)$   $(j = 1, ..., k)$ . Using the approach of Section 3, we obtain the truncated interval observations  $(L_i, R_i, V_i)$  (i =

 $1, \ldots, 295$ ). For purpose of comparison we also obtain the estimators of  $S(t)$  (denoted by  $(\hat{S}_E)$  by using the exact observations  $(T_i, V_i)$ 's (i.e. left-truncated data). Table 4 shows the results of the three estimators  $\hat{S}_M$ ,  $\hat{S}_n$  and  $\hat{S}_E$  at some selected values of t. Table 4 indicates that the differences between  $\hat{S}_M(t)$  and  $\hat{S}_E(t)$  (denoted by diff1) are smaller than that between  $\hat{S}_n(t)$  and  $\hat{S}_E(t)$  (denoted by diff2).

$\it t$	$\bar{S}_E(t)$	$S_M(t)$	$\hat{S}_n(t)$	diff1	diff2
10	0.835	0.819	0.813	$-0.016$	$-0.022$
15	0.684	0.669	0.665	$-0.015$	$-0.019$
20	0.577	0.565	0.559	$-0.012$	$-0.016$
25	0.456	0.447	0.443	$-0.009$	$-0.013$
30	0.372	0.359	0.354	$-0.013$	$-0.018$
35	0.287	0.276	0.271	$-0.011$	$-0.016$
40	0.204	0.193	0.188	$-0.011$	$-0.015$
45	0.158	0.150	0.148	$-0.008$	$-0.010$
50	0.114	0.104	0.101	$-0.010$	$-0.013$
55	0.102	0.094	0.090	$-0.008$	$-0.012$
60	0.091	0.085	0.082	$-0.006$	$-0.009$
70	0.070	0.066	0.062	$-0.004$	$-0.008$
80	0.052	0.047	0.046	$-0.005$	$-0.006$

Table 4. Estimation of the distribution function of the incubation time for AIDS Blood Transfusion Data

#### 5. Discussions

For interval-censored and left truncated data, Turnbull's algorithm leads to a self-consistent equation which is not in the form of an integral equation. Large sample properties of the NPMLE have not been previously examined because of, we believe, among other things, the lack of such an integral equation. In this article, we have presented a SCE using an integral equation and shown that the NPMLE is a solution of the integral equation. If we can show the consistency of the SCE under certain conditions then the consistency of the NPMLE can therefore be established. More research is needed to investigate this problem.

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# 國科會補助計畫衍生研發成果推廣資料表

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# 100 年度專題研究計畫研究成果彙整表







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